



A Review of VNA Calibration Methods

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Outline



- What is VNA Calibration?
- Measurement Errors
- Error Models: from 1 to N Ports
- Calibration
- Self-Calibration Algorithms
- Residual Calibration Errors
- Conclusion



What is VNA calibration?



- Calibration (by ISO) is the:
 - “...set of operations that establish, under specified conditions, the relationship between values of quantities indicated by a measuring instrument or measuring system, or values represented by a material measure or a reference material, and the corresponding values realized by standards.” [1]
- Two meanings of the VNA calibration are typically in use:
 - Instrument calibration at the manufacturer’s side
 - once in two years or so
 - Definition and removing of systematic measurement errors before measurement session
 - once a day or more often



Outline



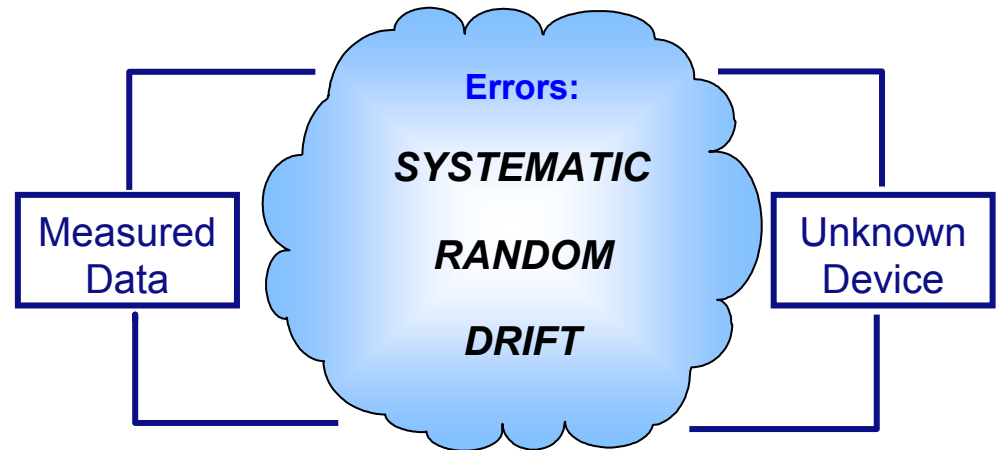
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Measurement Errors



- Can be grouped as:
 - Systematic
 - Random
 - Drift



- Drift and systematic errors can be defined by (re-)calibration
- Error correction procedure removes these errors from measurement results

Picture: Agilent Technologies



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Error Models: Influencing Factors



- Number of ports



2 ports



4 ports



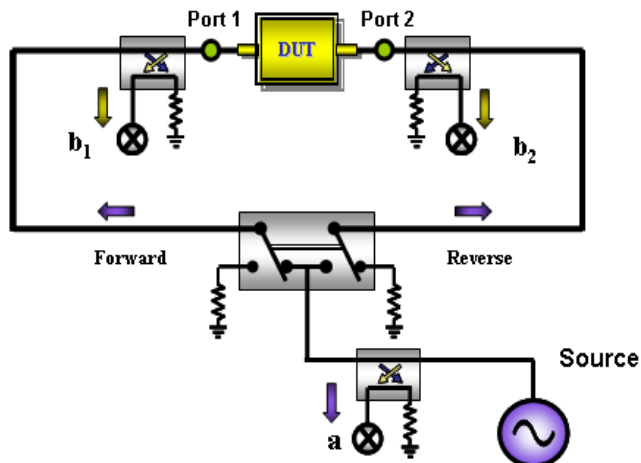
8 ports



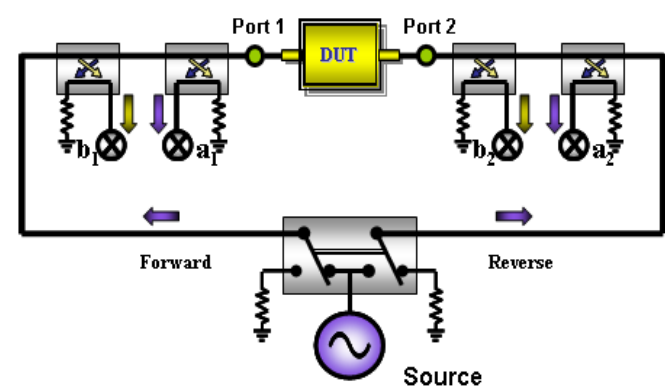
≤ 16 ports

- Receiver concept

Reference channel: $N=n+1$ receivers



Double reflectometer: $N=2n$ receivers



where :
 N - number of receivers
 n - number of ports

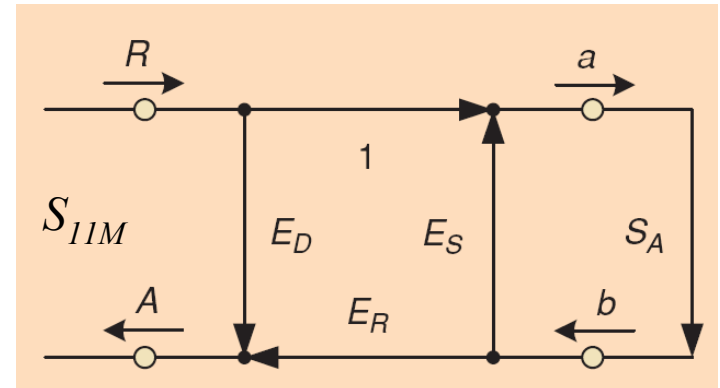
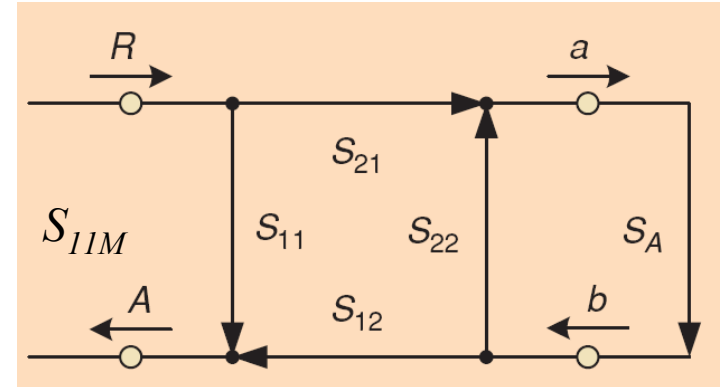


Error Models: One Port



- Over four error S-parameters
- Over three error terms [2]
 - Directivity, E_D
 - Source match, E_S
 - Reflection tracking, E_R
- Error correction:

$$S_{11A} = \frac{S_{11M} - E_D}{E_S(S_{11M} - E_D) + E_R}$$



where:

S_{11A} – actual DUT parameter

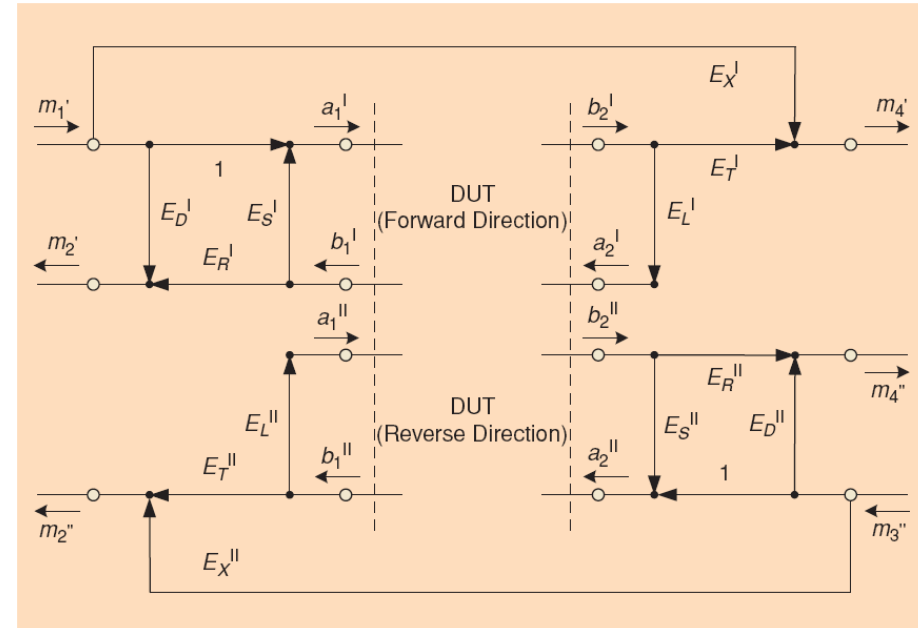
S_{11M} – measured DUT parameter



Error Models: Two Port



- Contains 10(12) error terms
- Additional terms:
 - Transmission tracking, E_T
 - Load match, E_L
 - Crosstalk, E_X
- Crosstalk (Isolation) E_X is typically omitted
- Error correction [3]:



$$a_1^I = m_1^I + \frac{E_S^I}{E_R^I} (m_2^I - E_D^I m_1^I), \quad b_1^I = \frac{1}{E_R^I} (m_2^I - E_D^I m_1^I), \quad b_2^I = \frac{m_4^I}{E_T^I}, \quad a_2^I = \frac{E_L^I m_4^I}{E_T^I},$$

$$\begin{pmatrix} b_1^I & b_1^{II} \\ b_2^I & b_2^{II} \end{pmatrix} = \begin{pmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{pmatrix} \begin{pmatrix} a_1^I & a_1^{II} \\ a_2^I & a_2^{II} \end{pmatrix}, \quad [K] = [Sx][L], \quad [Sx] = [K][L]^{-1}$$

where:

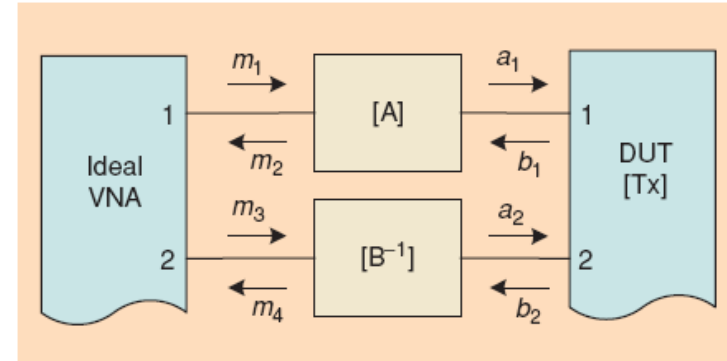
m – waves measured by the ideal VNA receivers;
 a, b – incident, transmitted/reflected waves, at the DUT plane;
 prime, double-prime parameters correspond to the forward and reverse measurement directions respectively.



Two Port Double Reflectometer



- Built off the transmission $[T]$ parameters [4]
- Two matrices $[A]$ and $[B]$
- 7 Error terms are in use:
 - Normalized to one term (A_{22})
- Error correction:



$$\begin{pmatrix} m_1' & m_1'' \\ m_2' & m_2'' \end{pmatrix} = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \begin{pmatrix} T_{11} & T_{12} \\ T_{21} & T_{22} \end{pmatrix} \begin{pmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{pmatrix}^{-1} \begin{pmatrix} m_3' & m_3'' \\ m_4' & m_4'' \end{pmatrix},$$

$$M = ATB^{-1}, \quad M = \begin{pmatrix} m_1' & m_1'' \\ m_2' & m_2'' \end{pmatrix} \begin{pmatrix} m_3' & m_3'' \\ m_4' & m_4'' \end{pmatrix}^{-1}, \quad T_X = A^{-1}M_X B$$

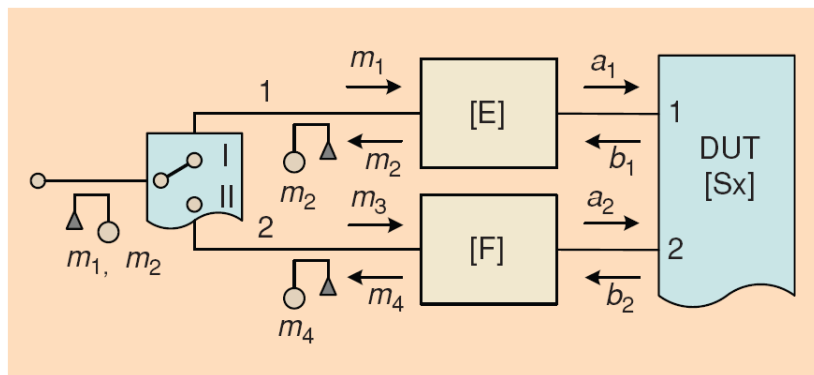
where:
 T_X – T-parameters of DUT;
 prime, double-prime parameters
 correspond to the forward and reverse
 measurement directions respectively.



Error Models: Multiport Cases



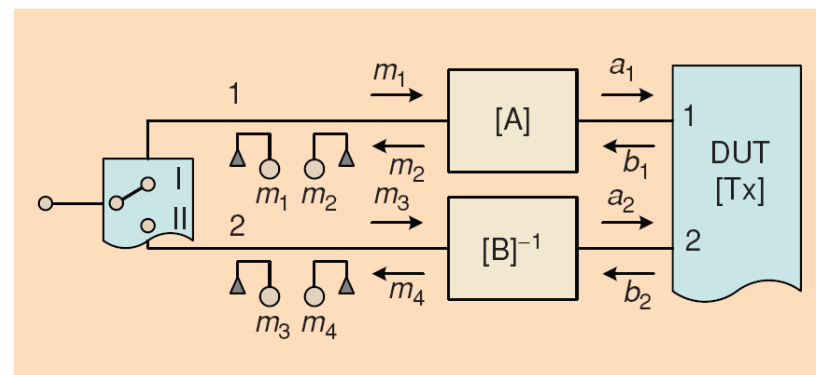
- Reference channel [4]



- Model can be extended by matrices $[G]$, $[H]$, ...
- Number of error terms is:

$$N = 2n^2 - 1$$

- Double reflectometer [5]



- Model can be extended by matrices $[B_{II}]$, $[B_{III}]$, ...
- Number of error terms is:

$$N = 4n - 1$$



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Calibration: One Port



- Three unknowns have to be defined

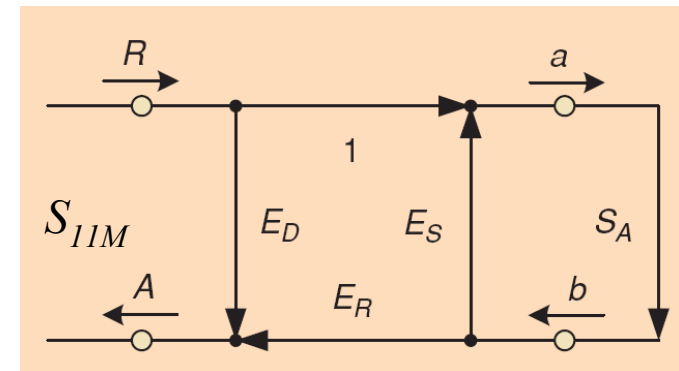
$$S_{11A} = \frac{S_{11M} - E_D}{E_S(S_{11M} - E_D) + E_R}$$

- Three independent measurement conditions are required

1: $E_D + S_{11A}^I S_{11M}^I E_R - S_{11A}^I (E_D E_S - E_R) = S_{11M}^I$

2: $E_D + S_{11A}^{II} S_{11M}^{II} E_R - S_{11A}^{II} (E_D E_S - E_R) = S_{11M}^{II}$

3: $E_D + S_{11A}^{III} S_{11M}^{III} E_R - S_{11A}^{III} (E_D E_S - E_R) = S_{11M}^{III}$



- Commonly used standards:
 - Short, Open, Load (SOL)



Calibration: Two Ports



10 Unknowns have to be defined

- Step 1. One-port SOL for Port 1:

$$E'_D, E'_S, E'_R$$

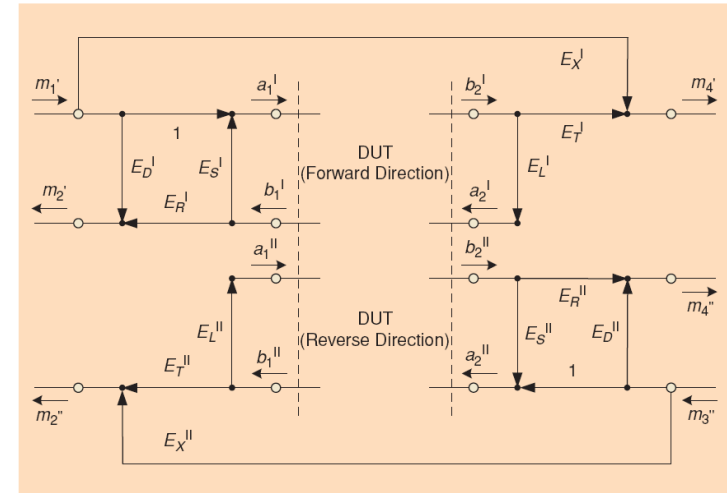
- Step 2. One-port SOL for Port 2:

$$E''_D, E''_S, E''_R$$

- Step 3. Connect two ports together (“Thru”):

$$E'_L = \frac{S'_{11M} - E'_D}{S'_{11M} E'_S - (E'_D E'_S - E'_R)}, \quad E'_T = S'_{21M} (1 - E'_S E'_L)$$

- Step 4. Same as Step 3 but in reverse direction: E''_L, E''_F



prime, double-prime parameters correspond to the forward and reverse measurement directions respectively.



Calibration SOL and SOLT



- Advantages
 - Can be applied on both reference channel and double reflectometer VNAs
 - Robust
- Drawbacks
 - All standards have to be either known or ideal
 - Not self-consistent



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Self-Calibration Algorithms: TRL [6]



Standards	Requirements	Unknown	Error Terms	Self-Calibration Product
<u>THRU</u>	Known: S_{11} , S_{21} , S_{12} , S_{22}	---	4	---
<u>LINE</u>	Known: S_{11} , S_{22} , length	S_{21} , S_{12} ,	2	Propagation constant γ
<u>REFLECT</u>	$S_{11}=S_{22}$ $S_{11}(S_{22})$ known within +/- 90 degree	S_{11} (S_{22})	1	S_{11} (S_{22})



Self-Calibration Algorithms: TRL



- Advantages
 - Traceable calibration and measurements (for air-lines)
 - Does not require ideal Open or Short
 - Self-consistent
- Drawbacks
 - Frequency limited. Many lines required for broadband measurements (e.g. multiline TRL)
 - Difficulties in on-wafer application
 - Sensitive to Reflect asymmetry



Self-Calibration Algorithms: LRM [7]



Standards	Requirements	Unknown	Error Terms	Self-Calibration Product
<u>LINE</u> (Thru)	Known: S_{11} , S_{21} , S_{12} , S_{22}	---	4	---
<u>MATCH</u> (Load)	Known: S_{11} , S_{22} $S_{11}=S_{22}$ $Z_{\text{MATCH}}=50 \text{ Ohm}$	---	2	---
<u>REFLECT</u>	$S_{11}=S_{22}$ $S_{11}(S_{22})$ known within +/- 90 degree	S_{11} (S_{22})	1	S_{11} (S_{22})



Self-Calibration Algorithms: LRM



- Advantages
 - Broadband
 - Self-consistent
- Drawbacks
 - Requires 50 Ohm Load
 - Sensitive to Load asymmetry and Reflect asymmetry



Self-Calibration Algorithms: SOLR [8]



Standards	Requirements	Unknown	Error Terms	Self-Calibration Product
<u>SHORT</u>	Known: S_{11} , S_{22}	---	2	---
<u>OPEN</u>	Known: S_{11} , S_{22}	---	2	---
<u>LOAD</u>	Known: S_{11} , S_{22}	---	2	---
<u>RECIPROC</u>	$S_{21}=S_{12}$ $S_{21}(S_{12})$ known within +/- 90 degree	S_{11} , S_{21} , S_{12} , S_{22}	1	S_{11} , S_{21} , S_{12} , S_{22}



Self-Calibration Algorithms: SOLR



- Advantages
 - Does not require known Thru
 - Self-consistent
- Drawbacks
 - All lumped standards (Open, Short, Load) should be either ideal or known



Self-Calibration Algorithms: QSOLT [9, 10]



Standards	Requirements	Unknown	Error Terms	Self-Calibration Product
<u>SHORT</u>	Known: S_{11} , S_{22}	---	1	---
<u>OPEN</u>	Known: S_{11} , S_{22}	---	1	---
<u>LOAD</u>	Known: S_{11} , S_{22}	---	1	---
<u>THRU</u>	Known: S_{11} , S_{21} , S_{12} , S_{22}	---	4	---



Self-Calibration Algorithms: QSOLT



- Advantages
 - Reduced calibration time
 - Improved quality of transmission measurements (vs. SOLT)
- Drawbacks
 - Poor measurement accuracy on the “virtually” calibrated port
 - Not self-consistent



Self-Calibration Algorithms: LRRM [11]



Standards	Requirements	Unknown	Error Terms	Self-Calibration Product
<u>THRU</u>	Known: S_{11} , S_{21} , S_{12} , S_{22}	---	4	---
<u>REFLECT</u> (as Open)	$S_{11}=S_{22}$ $S_{11}(S_{22})$ known within +/- 90 degree	S_{11} (S_{22})	1	S_{11} (S_{22})
<u>REFLECT</u> (as Short)	$S_{11}=S_{22}$ $S_{11}(S_{22})$ known within +/- 90 degree	S_{11} (S_{22})	1	S_{11} (S_{22})
<u>MATCH</u> (Load)	Known: S_{11} Not measured on the second port	---	1	---



Self-Calibration Algorithms: LRRM



- Advantages
 - Not sensitive to the Load asymmetry (only one Load is measured)
 - Does not require known Open and Short
 - Impedance element can be used as Load
 - Self-consistent
- Drawbacks
 - Poor measurement accuracy on second port
 - Sensitive to the measurement setup asymmetry
 - Requires known Load
 - Sensitive to the Reflect asymmetries



Self-Calibration Algorithms: LRM+ [12]



Standards	Requirements/ Conditions	Unknown	Error Terms	Self- Calibration Product
<u>LINE</u> (Thru)	Known: S_{11} , S_{21} , S_{12} , S_{22}	---	4	---
<u>MATCH</u> (Load)	Known: S_{11} , S_{22} $S_{11} \neq S_{22}$ Arbitrary impedance	---	2	---
<u>REFLECT</u>	$S_{11} = S_{22}$ $S_{11}(S_{22})$ known within +/- 90 degree	S_{11} (S_{22})	1	S_{11} (S_{22})



Self-Calibration Algorithms: LRM+



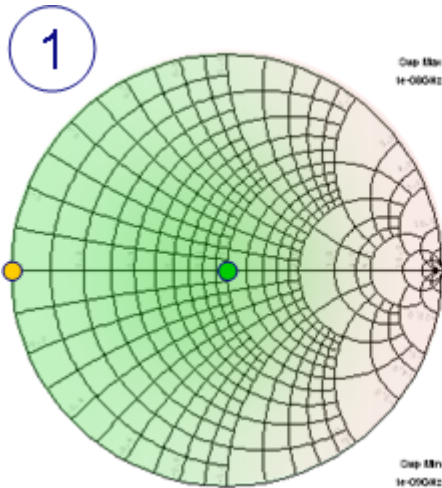
- Advantages
 - Not sensitive to Load asymmetry
 - Arbitrary impedance elements can be used as Loads
 - Does not require known Open or Short
 - Self-consistent
- Drawbacks
 - Requires known Loads
 - Sensitive to Reflect asymmetry



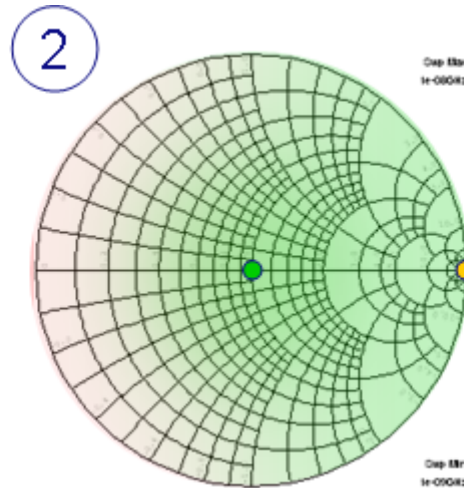
Self-Calibration Algorithms: RRMT [13]



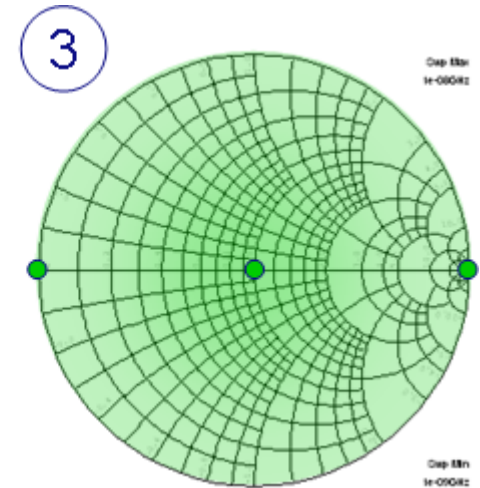
- RRMT concept: merge the best from 10- and 7-Term calibration in one



7-Term step: LRM+
with Short:
→ Model of the Short



7-Term step: LRM+
with Open:
→ Model of the Open



10-Term step: calibration with
fully known standards



Self-Calibration Algorithms: RRMT



Standards	Requirements	Unknown	Self-Calibration Product
<u>THRU</u>	Known: S_{11} , S_{21} , S_{12} , S_{22}	---	---
<u>REFLECT</u> (as Open)	$S_{11}=S_{22}$ $S_{11}(S_{22})$ known within +/- 90 degree	S_{11} (S_{22})	S_{11} (S_{22})
<u>REFLECT</u> (as Short)	$S_{11}=S_{22}$ $S_{11}(S_{22})$ known within +/- 90 degree	S_{11} (S_{22})	S_{11} (S_{22})
<u>MATCH</u> (Load)	Known: S_{11} , S_{22} $S_{11} \neq S_{22}$ Arbitrary impedance	---	---



Self-Calibration Algorithms: RRMT



- Advantages
 - Robust 10-Terms calibration algorithm
 - Not sensitive to the Load asymmetry
 - Arbitrary impedance elements can be used as Loads
 - Does not require known Open or Short
 - Self-consistent
- Drawbacks
 - Requires known Loads
 - Sensitive to Reflect asymmetry



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Residual Calibration Errors



- Calibration standards should fit requirements:

THRU	LINE*	OPEN	SHORT	LOAD (MATCH)	REFLECT	RECIPROC
Known: S_{11} , S_{21} , S_{12} , S_{22}	Known: S_{11} , S_{22} ; length	Known: S_{11} (S_{22})	Known: S_{11} (S_{22})	Known: S_{11}^{**} (S_{22})	$S_{11}=S_{22}$ $S_{11}(S_{22})$ known within +/- 90 degree	$S_{21}=S_{12}$ $S_{21}(S_{12})$ known within +/- 90 degree

- Standard fabrication tolerances, as well as insufficient models lead to residual calibration errors [14]

*For TRL

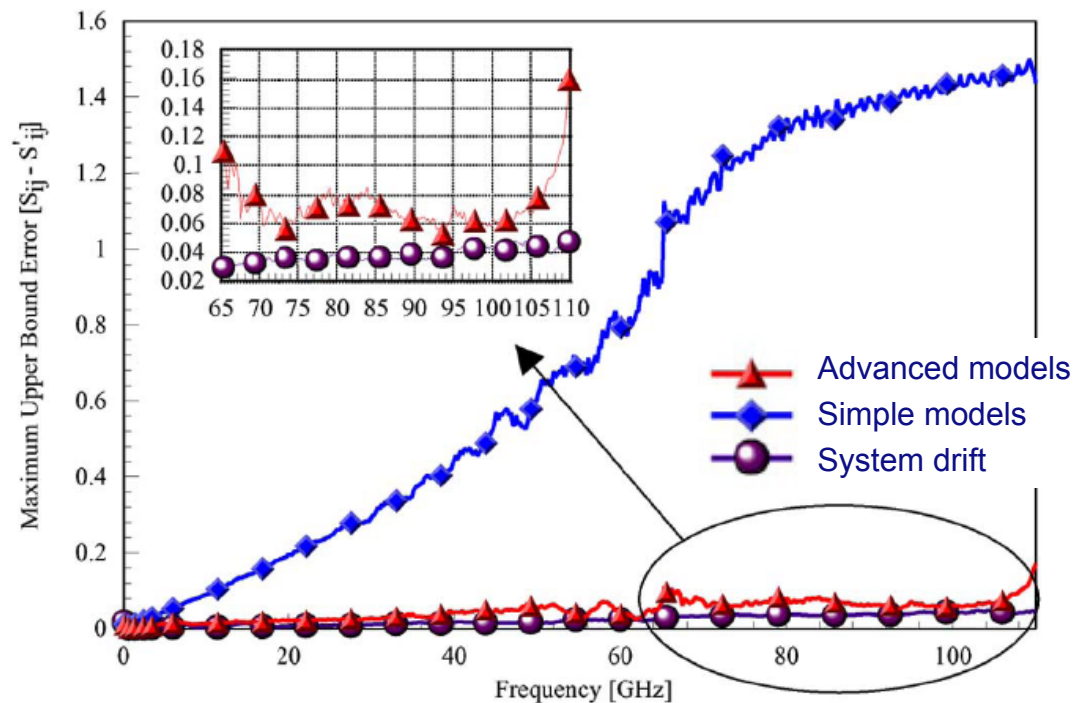
**50 Ohm for conventional LRM



Residual Calibration Errors: SOLT



- SOLT on GaAs with simplified and advanced models for Open, Short and Load [15]

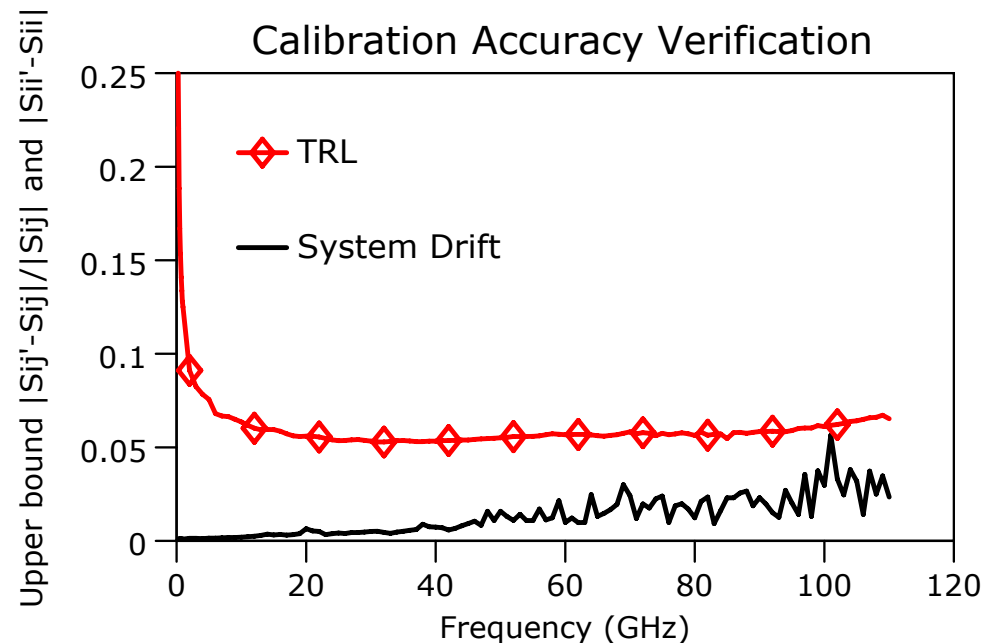
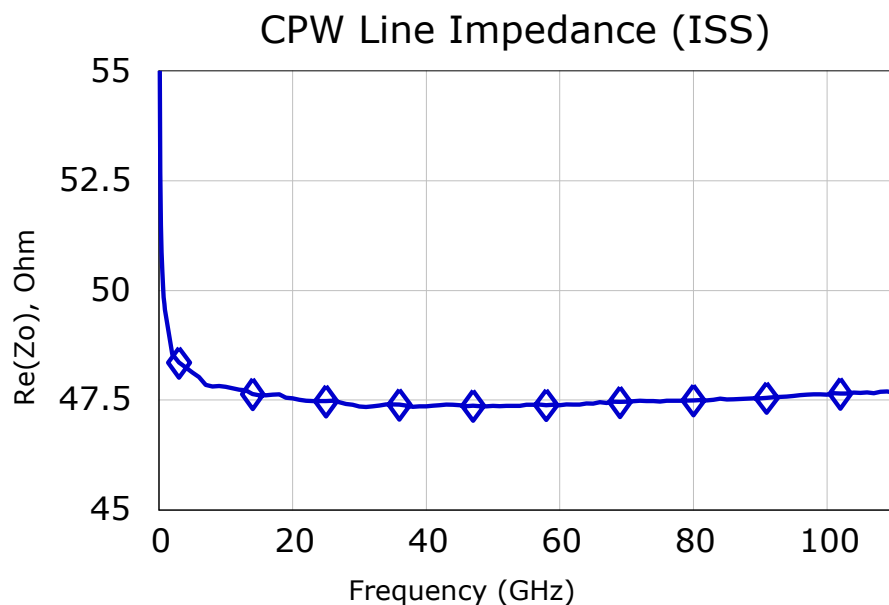




Residual Calibration Errors: TRL



- CPW TRL (4 Lines) on ISS with respect to the 50 Ohm calibration [16, 17]



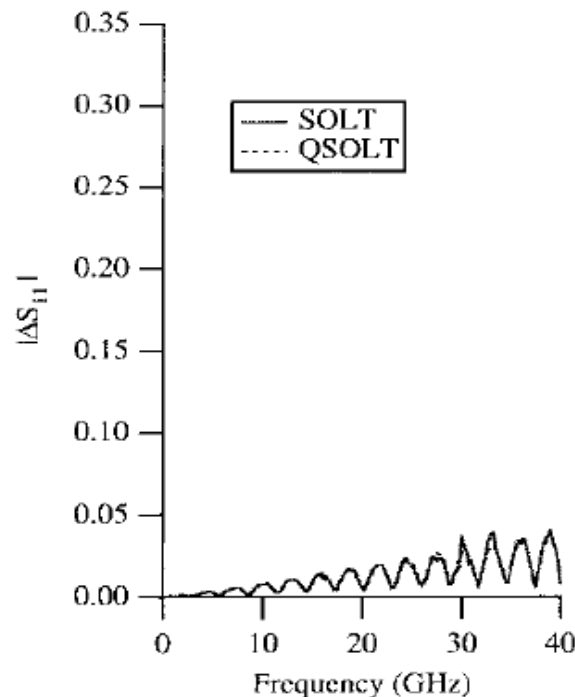


Residual Calibration Errors: QSOLT

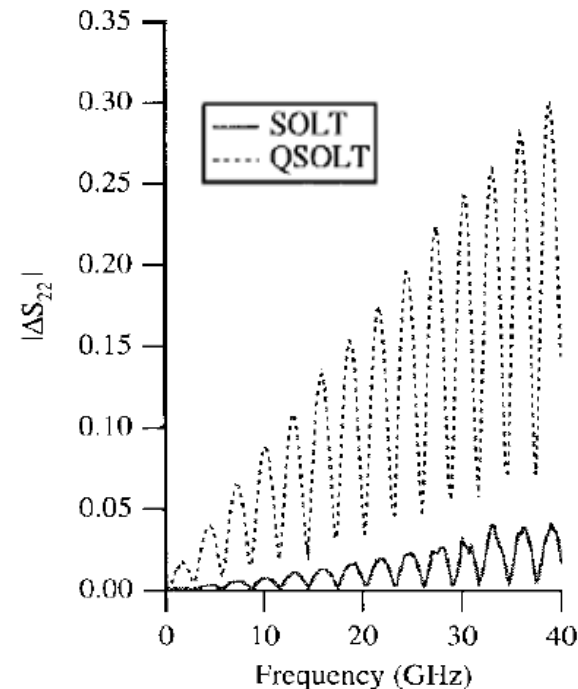


- QSOLT and SOLT with the same set of coaxial standards [18]

Port 1, Calibrated



Port 2, “Virtually” Calibrated

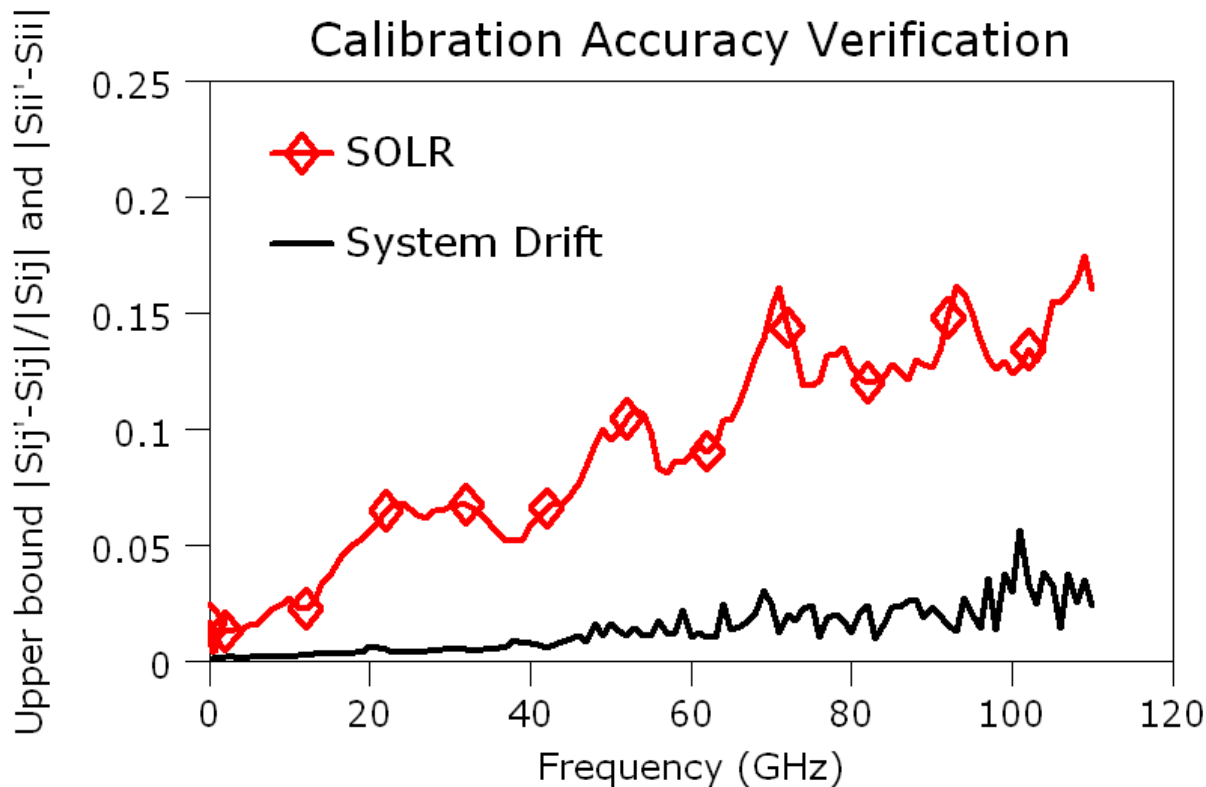




Residual Calibration Errors: SOLR



- SOLR on alumina with respect to 50 Ohm multiline TRL [17]

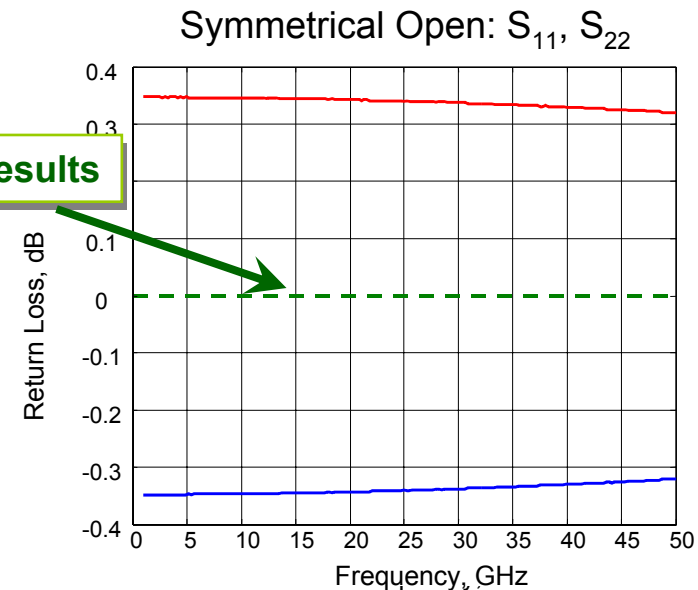
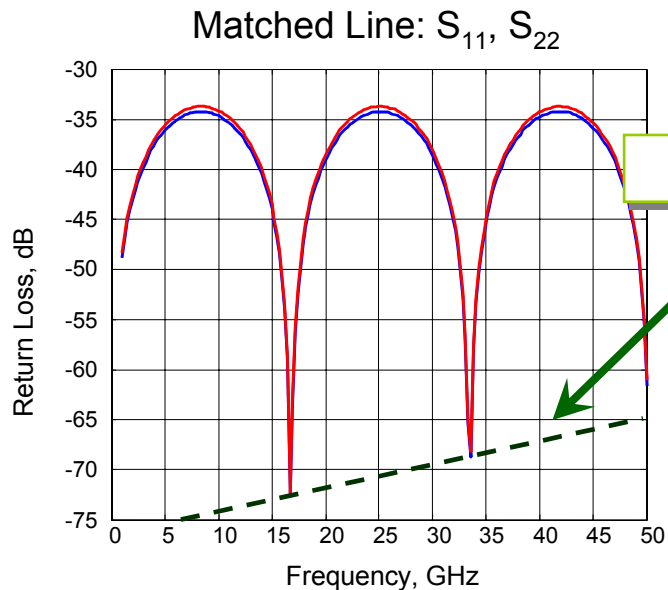




Residual Calibration Errors: LRM



- Load's asymmetry for LRM* with:
 - Load, Port 1: $R=51\ \Omega$, $X=0$
 - Load, Port 2: $R=49\ \Omega$, $X=0$
 - Short as reflect



Expected results

*Simulated results

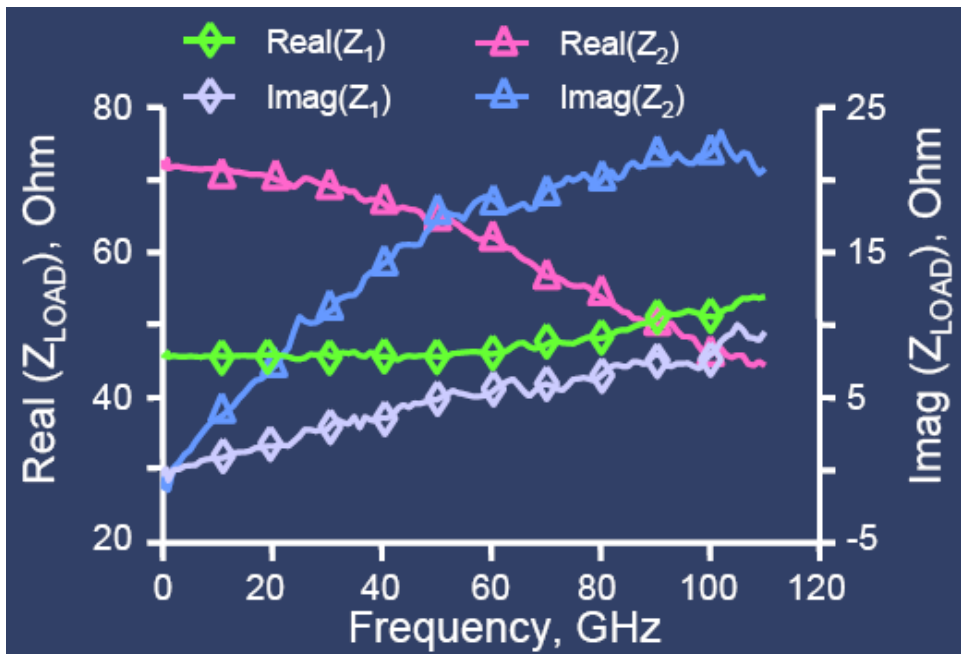


Residual Calibration Errors: LRM, LRM+

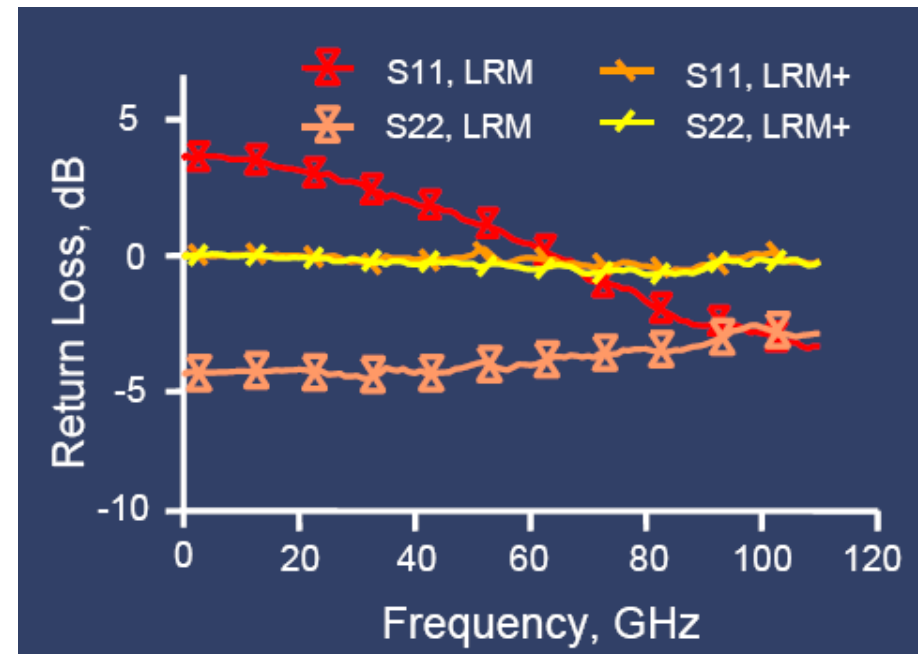


- Load's asymmetry for LRM and LRM+ (Short as reflect) on GaAs RM8130 [19]

Load Impedance



Symmetrical Open

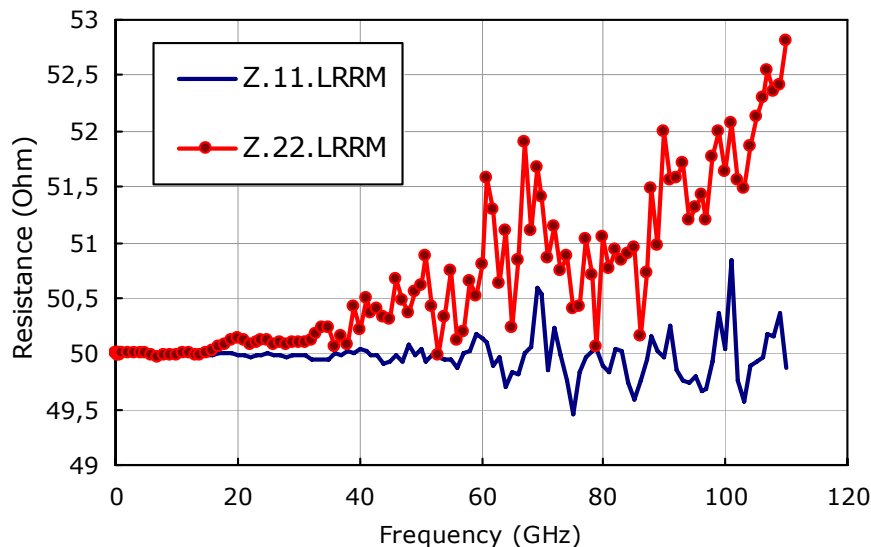




Residual Calibration Errors: LRRM



- System reference impedance Z_0 after enhanced LRRM* (with the Load measured on the VNA Port 1) on ISS [20]
- Verification measurements:
 - the same matched (50 Ohm) DUT, measured at Port 1, Port 2



$$S = \frac{Z_{DUT} - Z_0}{Z_{DUT} + Z_0}$$

$$Z_{0,PORT 2} \neq 50$$

$$S_{DUT,PORT 2} = ?$$



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Conclusion



- VNA calibration removes systematic measurement errors and instrument drift
- Difficulties in standard realization and modeling can be solved by self-calibration procedures
- “Virtual” calibration leads to poor measurement accuracy
- All VNA port should be calibrated using real standards
- Optimal calibration algorithm can be found for each measurement applications and system configuration



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